

Name: \_\_\_\_\_

Math 615 NADE (Bueler)

Friday, 24 March 2023

## Midterm Exam

**In class. No textbook, notes, or internet. 70 minutes. 100 points possible.**

1. (10 pts) Use Taylor's theorem to derive the centered finite difference (FD) approximation to  $u''(x)$  for an equally-spaced grid. (*Hints.* Denote the grid spacing by  $h$ . Use Taylor twice. Combine and cancel terms.) To state your final result, fill in the blanks at the bottom.

$$u''(x) = \frac{\boxed{\phantom{u''(x) = \frac{u(x+h) - 2u(x) + u(x-h)}{h^2}}}}{\boxed{\phantom{h^2}}} + O\left(h^{\boxed{\phantom{2}}}\right)$$

**2.** (10 pts) Consider the ODE BVP

$$(*) \quad u''(x) + 5u(x) = f(x), \quad u(0) = \alpha, \quad u(2) = \beta,$$

for  $f(x)$  a given continuous function and  $\alpha, \beta$  any real numbers. Propose an FD scheme, on an equally-spaced grid of  $m$  subintervals, for problem (\*). (*Hints.* Describe the grid. State the main FD equation. State/include how the boundary conditions are handled. Make the range of indices clear in each expression. You do not need to prove or explain anything.)

**3. (a)** (8 pts) For an ODE problem and an FD scheme, for example as on the previous page, define the *local truncation error*  $\tau^h$ . (*Hints.* You need only *define* it, not simplify or expand it.)

**(b)** (5 pts) Define what it means for an FD scheme to be *consistent*.

**(c)** (5 pts) Suppose an FD scheme with grid spacing  $h$  is applied to a linear ODE or PDE BVP. This generates a matrix equation

$$A^h U^h = F^h.$$

Define what it means for the scheme to be *stable*.

4. (10 pts) Consider a system of  $m$  nonlinear equations in  $m$  variables,

$$\begin{aligned} f_1(x_1, \dots, x_m) &= 0, \\ &\vdots \\ f_m(x_1, \dots, x_m) &= 0. \end{aligned}$$

and suppose each  $f_i$  is differentiable. We may write this system as “ $F(x) = 0$ ” where  $x \in \mathbb{R}^m$  and  $F(x) \in \mathbb{R}^m$ . State *Newton’s method* for the equations  $F(x) = 0$ . (*Hints.* The method can be stated as a simple pseudocode or as a MATLAB function; syntax is not critical. It should start with an initial iterate  $x^{[0]}$  and generate a sequence of iterates  $x^{[k]}$ , and have an appropriate termination criterion based on a tolerance parameter. *Required:* Make it clear which derivatives of  $F(x)$  are used, and how, using standard notation as appropriate. *Required:* Clearly identify any linear systems that need to be solved.)

5. (a) (5 pts) Compute the eigenvalues of the matrix

$$A = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 2 & -1 \\ 0 & -8 & 0 \end{bmatrix}.$$

(b) (5 pts) If  $\lambda_i$  is an eigenvalue of  $A$ , describe in a couple of sentences how to find a corresponding eigenvector. (*Hint.* Use complete sentences. *Required:* State the equation satisfied by the eigenvector.)

(c) (5 pts) For the matrix  $A$  in part (a), will the iteration

$$y_{k+1} = Ay_k$$

converge for any nonzero vector  $y_0 \in \mathbb{R}^3$ ? Explain, using precise language as appropriate.

6. (10 pts) For the ODE system

$$u'(t) = f(t, u(t)),$$

where  $u(t) \in \mathbb{R}^s$ , and supposing an initial condition  $u(t_0) = \eta$  for  $\eta \in \mathbb{R}^s$ , write a pseudocode for the *explicit midpoint (EM) method*. The user provides a final time  $t_f$  and a fixed number  $N$  of steps. (*Hint*. State the method as a pseudocode or MATLAB function; syntax is not critical.)

7. (10 pts) For the scalar ODE IVP

$$u'(t) = t - 5u(t), \quad u(0) = 3,$$

compute  $U^1$  from one step of the *backward Euler* method, assuming  $k = 0.5$ .

8. (7 pts) For a square matrix  $A \in \mathbb{R}^{m \times m}$ , define the *matrix exponential*  $e^A$ .

9. (10 pts) Sketch, in the  $(t, u)$  plane, and showing slopes for the locations where  $f(t, u(t))$  is evaluated, a picture/cartoon of a single step of the *explicit trapezoid (ET) method*:

$$U^* = U^n + kf(t_n, U^n)$$

$$U^{n+1} = U^n + \frac{k}{2} (f(t_n, U^n) + f(t_n + k, U^*))$$

(*Hint.* Annotate your sketch carefully.)

**Extra Credit.** (*3 pts*) Recalling the definitions and notation from problem **3**, prove the fundamental theorem of finite difference methods, essentially the Lax equivalence theorem, as it applies to ODE BVPs:

$$O(h^p) \text{ local truncation error} + \text{stability} \implies O(h^p) \text{ numerical error.}$$

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