

Homework #12

Due Monday 25 April, 2022 at 11:59pm.

Submit as a single PDF via Gradescope; see the Canvas page

canvas.alaska.edu/courses/7017

Textbook Problems from Strang, *Intro Linear Algebra*, 5th ed. will be graded for completion. Answers/solutions to these Problems are linked at

bueler.github.io/math314/resources.html

The **P** Problems will be graded for correctness. When grading these Problems, I will expect you to write explanations using complete sentences!

Put these Textbook Problems first on your PDF, in this order.

from Problem Set 6.4, pages 344–348: # 4, 5, 8

from Problem Set 8.1, pages 406–409: # 1, 3, 13, 17, 20, 24 (*Hint. Append columns.*)

from Problem Set 8.2, pages 417–419: # 1, 4, 5, 10, 11, 14, 27

*Put these **P** Problems next on your PDF, in this order.*

P57. (a) By hand calculation, find an orthogonal matrix Q which diagonalizes

$$S = \begin{bmatrix} 1 & 0 & 2 \\ 0 & -1 & -2 \\ 2 & -2 & 0 \end{bmatrix}$$

(Hints. Recall that if X is an invertible matrix of eigenvectors of A then X diagonalizes A in the sense that $AX = X\Lambda$ or $A = X\Lambda X^{-1}$, where Λ is diagonal. Recall that the columns of an orthogonal matrix are orthonormal vectors: $Q^T Q = I$. If $X = Q$ is orthogonal then $A = X\Lambda X^{-1} = Q\Lambda Q^T$.)

(b) Check your calculation using Matlab's `eig` command

$$[Q, D] = \text{eig}(S)$$

Explain any differences between your Q and the computed Q from Matlab.

P58. (a) What matrix A transforms $(1, 0)$ and $(0, 1)$ to (r, s) and (t, u) ?

(b) What matrix B transforms (a, b) and (c, d) to $(1, 0)$ and $(0, 1)$?

(c) What condition on a, b, c, d will make part (b) impossible?

(d) When $r = a, s = b, t = c,$ and $u = d$ then A and B are matrix inverses. Confirm this.

P59. Consider the symmetric matrices

$$A = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \quad B = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

(a) Which of these classes of matrices do A and B belong to?:

INVERTIBLE, ORTHOGONAL, PROJECTION, PERMUTATION, DIAGONALIZABLE

Explain, or show work which supports your answers.

(b) Which of these factorizations are possible for A and B ?:

$$LU, \quad X\Lambda X^{-1}, \quad Q\Lambda Q^T$$

(As usual, L is lower triangular with ones on diagonal, U is upper triangular, X is invertible, Λ is diagonal, and Q is orthogonal.) Explain, or show work which supports your answers.

(c) By hand calculation, find Q orthogonal and Λ diagonal so that $B = Q\Lambda Q^T$. (Hint. B has a repeated eigenvalue $\lambda = 0$, and you will need to find two orthogonal and normalized eigenvectors for this λ . Check your work in Matlab.)

P60. In this problem we consider transformations from $\mathbf{V} = \mathbb{R}^2$ to $\mathbf{W} = \mathbb{R}^2$.

(a) For each of these transformations, is it linear? (Show it is, or give a counterexample.) In either case, give a simplified formula for $T(T(\mathbf{v}))$:

- $T(\mathbf{v}) = -\mathbf{v}$
- $T(\mathbf{v}) = \mathbf{v} + (1, 1)$
- $T(\mathbf{v}) = (\text{do } 90^\circ \text{ rotation on } \mathbf{v}) = (-v_2, v_1)$
- $T(\mathbf{v}) = (\text{projection}) = \frac{1}{2}(v_1 + v_2, v_1 + v_2)$

(b) Show that if T is linear, i.e. $T(a\mathbf{v} + b\mathbf{w}) = aT(\mathbf{v}) + bT(\mathbf{w})$, then $T(T(\mathbf{v}))$ is also linear.

(Note that it is common in mathematics to write “ T^2 ” for the composition $T(T(\cdot))$ of a transformation T with itself, even if T is not linear, and/or T is not already represented by a matrix.)

P61. (a) Consider the vector space \mathbf{M} of 2 by 2 matrices. Show that the transpose transformation T , on \mathbf{M} , is linear: $T(A) = A^T$. (Hint. Not much to do! Fits on one line.)

(b) Try to find a 2 by 2 matrix B so that $T(A) = BA$. Show that no such matrix B exists! (Hint. Show that $BA = A^T$ being true for all matrices A is impossible.)

(c) If we rearrange the entries of a 2 by 2 matrix A into a column vector \mathbf{a} with four entries then we can do what is asked in (b). That is, show that there is a 4×4 matrix C so that $C\mathbf{a}$ is a column vector which is the rearrangement of A^T .