

## 8.4 The matrix exponential solves systems

a lecture for MATH F302 Differential Equations

Ed Bueler, Dept. of Mathematics and Statistics, UAF

Fall 2023

for textbook: D. Zill, *A First Course in Differential Equations with Modeling Applications*, 11th ed.

## solving the simplest ODEs

- *simplest scalar ODE:*

$$y' = ay \quad \text{has solution} \quad y(t) = ce^{at}$$

- *simplest system of ODEs:*

$$\mathbf{X}' = \mathbf{A}\mathbf{X} \quad \text{has solution} \quad \mathbf{X}(t) = e^{\mathbf{A}t}\mathbf{C}$$

- the last formula is new in §8.4

## what does $e^{\mathbf{A}t}$ mean?

- what does  $e^{\mathbf{A}t}$  mean?
  - what does  $e^{at}$  mean?
    - \* what does  $e^x$  mean? ← we know this one!

$$e^x = 1 + x + \frac{x^2}{2} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots = \sum_{k=0}^{\infty} \frac{x^k}{k!}$$

- *definition.* if  $\mathbf{A}$  is a square matrix and  $t$  is any number then

$$\begin{aligned} e^{\mathbf{A}t} &= \mathbf{I} + \mathbf{A}t + \mathbf{A}^2 \frac{t^2}{2} + \mathbf{A}^3 \frac{t^3}{3!} + \mathbf{A}^4 \frac{t^4}{4!} + \dots \\ &= \sum_{k=0}^{\infty} \mathbf{A}^k \frac{t^k}{k!} \end{aligned}$$

- note  $\mathbf{A}^0 = \mathbf{I}$  makes sense if we believe  $x^0 = 1$
- also recall  $0! = 1$

## like an exercise on Homework §8.4

- $e^{\mathbf{A}t} = \mathbf{I} + \mathbf{A}t + \mathbf{A}^2 \frac{t^2}{2} + \mathbf{A}^3 \frac{t^3}{3!} + \mathbf{A}^4 \frac{t^4}{4!} + \dots$
- *example 1.* use the above series to compute  $e^{\mathbf{A}t}$  and  $e^{-\mathbf{A}t}$ , in simplified form, if

$$\mathbf{A} = \begin{pmatrix} 3 & 0 \\ 0 & -1 \end{pmatrix}$$

## like an exercise on Homework §8.4

- *example 2.* use the series definition to compute  $e^{\mathbf{A}t}$ , in simplified form, if

$$\mathbf{A} = \begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ -1 & 3 & 0 \end{pmatrix}$$

## like an exercise on Homework §8.4

- *example 3.* use the series definition to compute  $e^{\mathbf{A}t}$ , in simplified form, if

$$\mathbf{A} = \begin{pmatrix} -3 & -3 & -3 \\ 1 & 1 & 1 \\ 2 & 2 & 2 \end{pmatrix}$$

## last two were special

- *example 1* illustrates that *diagonal* matrices are easy to exponentiate
- *example 2* and *example 3* had unusual matrices with the property that some power was the zero matrix:

$$\mathbf{A}^k = \mathbf{0}$$

- but the above are not typical cases
- for most  $\mathbf{A}$ :
  - $e^{\mathbf{A}t}$  has infinitely-many nonzero terms
  - the pattern is harder to see

## like an exercise on Homework §8.4

- *example 4.* use the series definition to compute  $e^{\mathbf{A}t}$ , in simplified form, if

$$\mathbf{A} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$



## derivative of $e^{\mathbf{A}t}$

- *fact 1.*

$$\frac{d}{dt} \left( e^{\mathbf{A}t} \right) = \mathbf{A}e^{\mathbf{A}t}$$

Proof.

$$\begin{aligned} \frac{d}{dt} \left( e^{\mathbf{A}t} \right) &= \frac{d}{dt} \left( \mathbf{I} + \mathbf{A}t + \mathbf{A}^2 \frac{t^2}{2} + \mathbf{A}^3 \frac{t^3}{3!} + \mathbf{A}^4 \frac{t^4}{4!} + \dots \right) \\ &= \mathbf{0} + \mathbf{A} + \mathbf{A}^2 \frac{2t}{2} + \mathbf{A}^3 \frac{3t^2}{3!} + \mathbf{A}^4 \frac{4t^3}{4!} + \dots \\ &= \mathbf{A} \left( \mathbf{I} + \mathbf{A}t + \mathbf{A}^2 \frac{t^2}{2} + \mathbf{A}^3 \frac{t^3}{3!} + \dots \right) = \mathbf{A}e^{\mathbf{A}t} \end{aligned}$$

□

- *fact 2.* if  $\mathbf{X}(t) = e^{\mathbf{A}t}\mathbf{C}$  then  $\mathbf{X}' = \mathbf{A}\mathbf{X}$
- *fact 3.* if  $\mathbf{X}(t) = e^{\mathbf{A}t}\mathbf{C}$  then  $\mathbf{X}(0) = \mathbf{C}$

## the matrix exponential solves systems

in summary:

- 1 for the ODE

$$\mathbf{X}' = \mathbf{A}\mathbf{X}$$

the general solution is

$$\mathbf{X}(t) = e^{\mathbf{A}t}\mathbf{C}$$

where  $\mathbf{C} = \begin{pmatrix} c_1 \\ \vdots \\ c_n \end{pmatrix}$  is a vector of unknown constants

- 2 for the ODE IVP

$$\mathbf{X}' = \mathbf{A}\mathbf{X}, \quad \mathbf{X}(0) = \mathbf{X}_0$$

the solution is

$$\mathbf{X}(t) = e^{\mathbf{A}t}\mathbf{X}_0$$

use a computer ...

- for the ODE IVP

$$\mathbf{X}' = \mathbf{A}\mathbf{X}, \quad \mathbf{X}(0) = \mathbf{C}$$

suppose you want the solution at time  $t$ :

$$\mathbf{X}(T) = e^{\mathbf{A}t}\mathbf{C}$$

- with Matlab or Octave:

```
>> A = [...];           % enter square matrix A
>> C = [...];           % enter column vector C
>> t = ...               % set the time
>> expm(A*t) * C        % bam! done!
```

- `expm()` computes the matrix exponential
  - be careful ... `exp()` is *not* what you want

## ... for fast numbers

- *example 5.* solve the initial value problem for  $x(2), y(2), z(2)$ :

$$x' = 2x - 5y + z \qquad x(0) = -2$$

$$y' = -x + y + 3z \qquad y(0) = 0$$

$$z' = x - 2y - z \qquad z(0) = 3$$

*solution.*

```
>> A = [2 -5 1; -1 1 3; 1 -2 -1];
```

```
>> C = [-2; 0; 3];
```

```
>> expm(A*2) * C
```

```
ans =
```

```
    -1227.9
```

```
     68.564
```

```
   -381.69
```

so:  $x(2) = -1227.9, y(2) = 68.564, z(2) = -381.69$

## can you check it?

- what tool would help us quickly check previous slide result?
  - consider all the tools in the whole course ...
- *answer.* the most general tool is **numerical approximation**
- *example 5, cont.* check the solution on the previous slide

*solution.*

```
>> f = @(t,U) [2*U(1)-5*U(2)+U(3); ...  
              -U(1)+U(2)+3*U(3); ...  
              U(1)-2*U(2)-U(3)];  
>> [tt,UU] = ode45(f,[0,2],[-2;0;3]);  
>> UU(end,:)  
ans =  
    -1227.9      68.565    -381.7
```

## by-hand usage?

- as long as we can compute  $e^{\mathbf{A}t}$  by hand, we can solve an ODE by hand using the matrix exponential
- *example 6.* use  $\mathbf{X}(t) = e^{\mathbf{A}t}\mathbf{C}$  to find the general solution of the given system

$$\mathbf{x}' = \begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ -1 & 3 & 0 \end{pmatrix} \mathbf{x}$$

## expectations

- to learn this material, just listening to a lecture is *not* enough
  - *read* section 8.4
  - *read* and do Homework 8.4
- I hope you have learned something from this course!
  - perhaps even found it interesting?
  - note that
    - MATH 302 discrete mathematics
    - MATH 314 linear algebra
    - STAT 300 probability and statistics
    - MATH 265 introduction to mathematical proofare courses of more-or-less comparable level to MATH 302
  - a mathematics minor requires calculus I,II,III ✓, and three MATH courses at the 300/400 level (including MATH 265 and STAT 300 as special cases) ... ✓ on one of those!