

4.3 Homogeneous linear equations with constant coefficients

a lecture for MATH F302 Differential Equations

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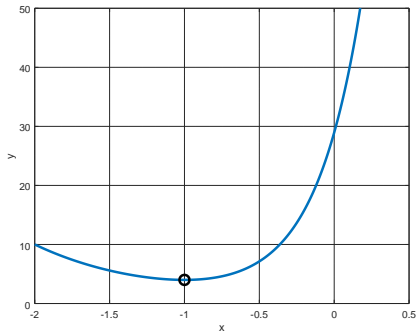
for textbook: D. Zill, *A First Course in Differential Equations with Modeling Applications*, 11th ed.

linear, homogeneous, constant-coefficient

- recall from §4.1 slides that linear DEs which are homogeneous and constant-coefficient **always have exponential solutions**
 - *fact*: you can always find at least one solution $y = e^{mx}$
 - but each of the underlined words is important to this fact
- *example 1*: solve the ODE IVP

$$y'' - 2y' - 4y = 0, \quad y(-1) = 4, \quad y'(-1) = 0$$

example 1, finished



example 1: how I did it

- here is how I solved for the constants and made the figure using Matlab:

```
w = 1-sqrt(5); z = 1+sqrt(5);
A = [exp(-w), exp(-z); w*exp(-w), z*exp(-z)];
b = [4; 0];
c = A \ b           % get: c(1)=0.8409, c(2)=28.119

x = -2:.01:1;
y = c(1) * exp(w*x) + c(2) * exp(z*x);
plot(x,y), grid on, xlabel x, ylabel y
axis([-2 0.5 0 50])
hold on, plot(-1,4,'ko','markersize',12), hold off
```

- I am committed to helping you use a computer for math!

example 2

- *example 2*: find the general solution of the ODE

$$y'' + y = 0$$

Euler's helpful identity

- Euler recognized the connection between imaginary numbers and trig functions:

$$e^{i\theta} = \cos \theta + i \sin \theta$$

- *exercise*: Explain *Euler's identity* above using the Taylor series of e^x , $\cos x$, $\sin x$ at basepoint $x_0 = 0$. Also draw a picture.

example 3

- from Euler's identity we also know

$$e^{a+ib} = e^a(\cos b + i \sin b)$$

- *example 3*: find the general solution of the ODE

$$y'' - 4y' + 5y = 0$$

the major facts of §4.3

for constant-coefficient and homogeneous linear ODEs

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \cdots + a_1 y' + a_0 y = 0$$

- substitution of $y = e^{mx}$ yields (polynomial) *auxiliary equation*

$$a_n m^n + a_{n-1} m^{n-1} + \cdots + a_1 m + a_0 = 0$$

- any polynomial eqn. has at least one *complex* root (solution)
 - auxiliary eqn. has at least 1 and at most n distinct roots
 - some roots may be repeated
- there is a recipe (next slide!) which generates a fundamental set of n real solutions and a general solution to the ODE:

$$y_1(x), \dots, y_n(x) \implies y(x) = c_1 y_1(x) + \cdots + c_n y_n(x)$$

main recipe of §4.3

find all roots of the auxiliary equation

$$a_n m^n + a_{n-1} m^{n-1} + \cdots + a_1 m + a_0 = 0$$

and then build a fundamental solution set this way:

case I: if m is a real root then

$$e^{mx} \text{ is in the set}$$

case II: if m is a real root which is repeated k times then

$$e^{mx}, xe^{mx}, \dots, x^{k-1}e^{mx} \text{ are in the set}$$

case III: if $m = a \pm ib$ is a complex root then

$$e^{ax} \cos(bx), e^{ax} \sin(bx) \text{ are in the set}$$

exercise 5 in §4.3

- *exercise 5*: find the general solution of the second-order DE

$$y'' + 8y' + 16y = 0$$

exercise 23 in §4.3

- *exercise 23*: find the general solution of the higher-order DE

$$y^{(4)} + y''' + y'' = 0$$

exercise 55 in §4.3

- *exercise 55*: find a constant-coefficient, homogeneous linear DE whose general solution is

$$y(x) = c_1 e^{-x} \cos x + c_2 e^{-x} \sin x$$

like exercise 69 in §4.3

- *like exercise 69*: solve the ODE IVP

$$2y^{(4)} + 13y''' + 21y'' + 2y' - 8y = 0$$

$$y(0) = -2, y'(0) = 6, y''(0) = 3, y'''(0) = \frac{1}{2}$$

hint. you may use a computer algebra system (CAS)

exercise 69: how to do it

```
>> m = roots([2,13,21,2,-8])'  
m =  
    -4    -2    -1    0.5  
>> A = [1 1 1 1; m; m.^2; m.^3]  
A =  
    1    1    1    1  
   -4   -2   -1   0.5  
   16    4    1   0.25  
  -64   -8   -1   0.125  
>> b = [-2 6 3 0.5]';  
>> c = A \ b  
c =  
  -0.48148  
    5.4  
 -12.222  
    5.3037
```

conclusion: a computer is very effective ... if you know where you are going

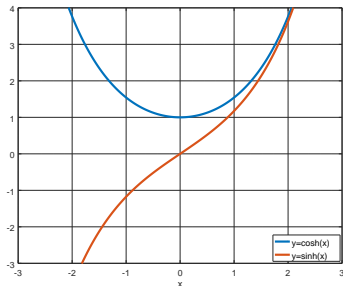
hyperbolic functions

- Euler's identity $e^{i\theta} = \cos \theta + i \sin \theta$, for complex exponentials, has an analog for real exponentials
- by definition:

$$\cosh x = \frac{e^x + e^{-x}}{2}$$

$$\sinh x = \frac{e^x - e^{-x}}{2}$$

- the even and odd parts of the exponential, resp.
 - called *hyperbolic* functions
-
- it is easy to see that
 - $e^x = \cosh x + \sinh x$
 - $(\cosh x)' = \sinh x$, $(\sinh x)' = \cosh x$
 - $y = c_1 \cosh x + c_2 \sinh x$ is a general solution to $y'' - y = 0$



some nice cases

- the following general solutions can all be computed by substituting $y = e^{mx}$, and getting the auxiliary equation, etc.
- ... but it is good to *quickly* apply these special cases:

	has general solution	
$y' = ky$	\longrightarrow	$y = Ae^{kx}$
$y'' + k^2y = 0$	\longrightarrow	$y = c_1 \cos(kx) + c_2 \sin(kx)$
$y'' - k^2y = 0$	\longrightarrow	$\left[\begin{array}{l} y = c_1 e^{kx} + c_2 e^{-kx} \\ \text{or} \\ y = b_1 \cosh(kx) + b_2 \sinh(kx) \end{array} \right]$
$y'' = 0$	\longrightarrow	$y = c_1 + c_2x$

expectations

to learn this material, just listening to a lecture is *not* enough

- *read* section 4.3 in the textbook
- find YouTube videos on “second order differential equations”
... then look for the constant-coefficient case
- for §4.3 you at least need to know these terms:

homogeneous

linearly (in)dependent

Wronskian

fundamental set of solutions

linear combination

general solution

- when we go back to §4.2: why does the repeated-roots case generate additional linearly-independent solutions via extra factors of “ x ”?