1.1 Definitions and Terminology a lecture for MATH F302 Differential Equations

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textbook: D. Zill, A First Course in Differential Equations with Modeling Applications, 11th ed.

### basic

• a *differential equation* is an equation with a derivative somewhere in it

# definitions

- idea: a differential equation contains an *unknown function* which we want to find
- an *ordinary differential equation* (ODE) uses ordinary derivatives (as in calculus I and II)
  - $\circ~$  primes (y'=dy/dx) or dots  $(\dot{y}=dy/dt)$  are often used to denote ordinary derivatives
  - examples of ODEs:

$$\frac{dy}{dx} = x + y^2 \qquad y(x) \text{ is unknown function}$$
  

$$y' = x + y^2 \qquad \dots \text{ exactly the same}$$
  

$$\frac{d^2u}{dt^2} = -cu \qquad u(t) \text{ is unknown function}$$
  

$$\ddot{u} = -cu \qquad \dots \text{ exactly the same}$$

• the unknown function in an ODE depends on one variable

# contrast with PDEs

- MATH 302 is about ODEs
- ... but there are also *partial differential equations* (PDEs)
  - subscripts are often used to denote partial derivatives
  - examples:

$$\begin{array}{l} \frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} & u(t,x) \text{ is unknown function} \\ u_{tt} = c^2 u_{xx} & \dots \text{ exactly the same PDE} \\ w_t = k(w_{xx} + w_{yy}) & w(t,x,y) \text{ is unknown function} \end{array}$$

- the unknown function in a PDE depends on more than one variable
- do not worry about PDEs!
  - they are covered in MATH 432
  - I am just explaining here why people say "ordinary"

#### order

- the *order* of a differential equation is the maximum number of derivatives
  - $\circ\;$  order has nothing to do with powers or exponentials
  - $\circ~$  most of the differential equations in MATH 302 have order 1 or order 2
- examples:

• 
$$y' = x + y^2$$
 has order one

- $\ddot{u} = -cu$  has order two
  - c is just a constant in this context

• 
$$y^3 + \frac{d^4y}{dx^4} = \left(\frac{d^2y}{dx^2} + \sin x\right)^5$$
 has order four

### two main operations on ODEs

- there is more terminology to come ... but let's do something
- two common operations with differential equations are
  - verify that a given function is a solution
  - construct a solution ("solve the differential equation")
- example: verify that  $y(x) = \sin(3x)$  solves y'' + 9y = 0

• *example*: construct a solution to  $y' = y^2$ 

#### visualization of solutions

- a given differential equation generally has many solutions
- example (a): show that for any value of the parameter A the function  $y(x) = Ae^{-x^2/2}$  solves  $\frac{dy}{dx} = -xy$

• example (b): sketch several particular solutions from (a)

### linear

- back to terminology
- a differential equation is *linear* if it can be written as a sum with only first powers on the unknown function and its derivatives
- examples:

•  $3y'' - 7y' + 8y = \sin x$  is linear because it is in the form

$$a_2(x)\frac{d^2y}{dx^2} + a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

•  $x\frac{y'}{y} = x^2 + 5$  is linear because it it *can* be written in the form

$$a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

(set:  $a_1(x) = x$ ,  $a_0(x) = -x^2 - 5$ , g(x) = 0)

# nonlinear

- linear differential equations are special and easier
  - nature has been generous by allowing good models of surprisingly-many situations to be built using linear differential equations
- most differential equations are *nonlinear* which only means they are not linear
- examples:
  - $y' = y^2$  is nonlinear
  - $y'' + \sin y = 0$  is nonlinear
- one way to understand MATH 302:
  - we will be able to solve *some* nonlinear ODEs
  - we will be systematic about solving linear ODEs

# implicit solution

• first, remember *implicit differentiation* 

• example: find dy/dx if  $x \sin y + y^2 = \ln x$ 

• the statement "verify [this implicitly-defined function] is a solution of [this differential equation]" asks for implicit differentiation

• example: verify  $y = e^{xy}$  defines a solution of  $(1 - xy)y' = y^2$ 

#### extras

the book mentions more terminology; none of this is terribly important, but it is used in the rest of the semester:

- page 5 normal form means the highest derivative is on the left; the normal form of  $y' y^2 = 0$  is  $y' = y^2$ , and the normal form of  $u'' + 9u = e^t$  is  $u'' = e^t 9u$
- page 7 a function y(x) can be discontinuous but when the book uses the term *solution* for y(x) then it solves a differential equation *and* we assume it is continuous on some interval
- page 11 a function like  $F(x) = \int_a^x g(t) dt$  is an *integral-defined* function; the most important thing to know is that the derivative is easy: F'(x) = g(x)

see Wed. 30 August worksheet

# standard expectations

**expectations**: to learn this material, just listening to a lecture is *not* enough

- please *read* section 1.1 in the textbook
  - $\circ~$  and browse section 1.2  $\,$
- please do the Homework for section 1.1
- please *look around* the bueler.github.io/math302 website
- please find other videos and related content!