



$$\mathcal{B} = \{ \quad \}, \quad B = \begin{bmatrix} \quad \\ \quad \\ \quad \end{bmatrix}, \quad \underline{Bx_B = b} \implies x_B = \begin{bmatrix} \quad \\ \quad \\ \quad \end{bmatrix}, \quad c_B = \begin{bmatrix} \quad \\ \quad \\ \quad \end{bmatrix}$$

$$\mathcal{N} = \{ \quad \}, \quad N = \begin{bmatrix} \quad \\ \quad \\ \quad \end{bmatrix}, \quad x_N = \begin{bmatrix} \quad \\ \quad \\ \quad \end{bmatrix}, \quad c_N = \begin{bmatrix} \quad \\ \quad \\ \quad \end{bmatrix}$$

$$\underline{B^T \lambda = c_B} \implies \lambda = \begin{bmatrix} \quad \\ \quad \end{bmatrix} \implies \underline{s_N = c_N - N^T \lambda} = \begin{bmatrix} \quad \\ \quad \\ \quad \end{bmatrix}$$

$$\boxed{s_N \geq 0? \text{ stop with optimum}} \quad s_N \xrightarrow{\text{index of min}} q = \boxed{\quad} \implies \underline{Bd = A_q} \implies d = \begin{bmatrix} \quad \\ \quad \end{bmatrix}$$

$$\boxed{d \leq 0? \text{ stop, unbounded}} \quad \left\{ \frac{(x_B)_i}{d_i} \right\} = \left\{ \quad \right\} \quad \text{index of min over } d_i > 0 \quad p = \boxed{\quad}$$

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