

## Assignment #9

Due *Tuesday, 2 May 2006.*

**I.** Read the handout “The hydrogen atom and the periodic table,” lecture III.19 from *The Feynman Lectures in Physics*. Note the sketch Fig. 19-6, which I will not attempt to reproduce.

**II.** Again, read chapter 19 from RILEY, HOBSON, & BENCE, paying special attention to expansions in “spherical polars.” Read chapter 24 very lightly.

**III.** Do exercises on the rotation group in the plane:

**Exercise P.** Let  $G$  be the set of all  $2 \times 2$  matrices of the form

$$R_\theta = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

for some  $\theta \in [0, 2\pi)$ . Show that  $G$  satisfies the definition of a *group* on page 885, where the product operation “ $\bullet$ ” is ordinary matrix multiplication in this case. Give a formula for  $R_\theta^{-1}$ . [Regarding the associative law, but only that law, you may refer to a clear reference if you find one. Note that the standard name for this  $G$  is “ $SO(2)$ ,” a name which I will explain in class.]

**Exercise Q.** Do the following exercise *by hand*; the point is that you must think through where points go. I don’t care if you are a bad sketch artist—I want you to think about the pictures associated to the action of rotations on vectors and on functions!

(a) Let  $\theta_1 = \pi/6$ ,  $\theta_2 = 3\pi/2$ . Pick two vectors  $\mathbf{v}_1, \mathbf{v}_2$  in the plane, with different directions and different nonzero lengths just to make the picture fairly general, and draw a clear picture showing all of the following six vectors in the same diagram:

$$\mathbf{v}_1, \mathbf{v}_2, R_{\theta_1} \mathbf{v}_1, R_{\theta_1} \mathbf{v}_2, R_{\theta_2} \mathbf{v}_1, R_{\theta_2} \mathbf{v}_2.$$

(b) Given

$$f(x, y) = f \left( \begin{bmatrix} x \\ y \end{bmatrix} \right),$$

an ordinary scalar function on the plane with its input point thought of as a vector, and given an element  $R_\theta$  of the rotation group  $G = SO(2)$  above, define

$$(R_\theta f)(x, y) = f \left( R_\theta^{-1} \begin{bmatrix} x \\ y \end{bmatrix} \right)$$

for all points  $(x, y)$  in the plane. For each of  $\theta_i$  in part (a), and for the two functions  $g(x, y) = x^2$  and  $h(x, y) = (x - y)^{-2}$ , sketch the graphs of  $z = g(x, y)$ ,  $z = h(x, y)$ ,  $z = (R_{\theta_1} g)(x, y)$ ,  $z = (R_{\theta_1} h)(x, y)$ ,  $z = (R_{\theta_2} g)(x, y)$ ,  $z = (R_{\theta_2} h)(x, y)$  in six separate figures. [Yes, I am asking for six different 3D surface graphs.] Finally, explain in a couple of sentences why “ $R_\theta^{-1}$ ” occurs in the definition of the action of  $R_\theta$  on a function  $f$ .

**IV.** Do one big exercise from RILEY, HOBSON, & BENCE:

### 19.17.

[Note that in the interior of the spherical shell the potential  $u$  solves  $\nabla^2 u = 0$ . The hint on this problem says “you will need to use the result of exercise 17.7,” which is true.]