

Selected Solutions to Assignment #8

These problems were graded at 3 points each for a total of 24 points.

5.2 #2. Rewrite as

$$\begin{aligned} Dx - 3y &\stackrel{(i)}{=} 0 \\ -2x + (D + 1)y &\stackrel{(ii)}{=} 0. \end{aligned}$$

Combine by $2(i) + D(ii)$ to get: $D(D + 1)y - 6y = 0$ or $y'' + y' - 6y = 0$. This second order equation has auxiliary equation $r^2 + r - 6 = 0$ or $(r + 3)(r - 2) = 0$ so $r = -3, +2$. Thus

$$\begin{aligned} x(t) &= -c_1 e^{-3t} + (3/2)c_2 e^{2t} \\ y(t) &= c_1 e^{-3t} + c_2 e^{2t}. \end{aligned}$$

Note that once $y(t)$ is found we find $x(t)$ most easily by (ii) : $x = (1/2)(y' + y) = (1/2)(-3c_1 e^{-3t} + 2c_2 e^{2t} + c_1 e^{-3t} + c_2 e^{2t})$. By setting $C_1 = -c_1$ and $C_2 = (3/2)c_2$, our solution is equivalent to

$$\begin{aligned} x(t) &= C_1 e^{-3t} + C_2 e^{2t} \\ y(t) &= -C_1 e^{-3t} + (2/3)C_2 e^{2t}. \end{aligned}$$

5.2 #8. The approach is similar to above. Combine $(D + 4)(i) - (D - 1)(ii)$ to get an equation for x : $(D + 4)(D - 3)[x] - (D - 1)(D + 1)[x] = (D + 4)t - (D - 1)1$ or $(D - 12 + 1)[x] = 1 + 4t + 1$ or

$$x' - 11x = 4t + 2.$$

This first order linear equation has solution by integrating factors. Namely,

$$\begin{aligned} \frac{d}{dt} (e^{-11t} x(t)) &= (4t + 2)e^{-11t} \\ e^{-11t} x(t) &= \int (4t + 2)e^{-11t} dt \\ e^{-11t} x(t) &= -(4t + 2) \frac{e^{-11t}}{11} + \int 4 \frac{e^{-11t}}{11} dt = -\frac{1}{11} (4t + 2)e^{-11t} - \frac{4}{11} \frac{e^{-11t}}{11} + C \end{aligned}$$

So

$$x(t) = -\frac{1}{11}(4t + 2) - \frac{4}{121} + C e^{11t} = -\frac{4}{11}t - \frac{26}{121} + C e^{11t}.$$

How to get $y(t)$? Either of the original equations is a first-order differential equation for $y(t)$. Choosing the first equation, and simplifying I get:

$$y' - y = -\frac{1}{11}t - \frac{34}{121} - 8C e^{11t}.$$

This is first order linear. The solution is

$$y(t) = \frac{1}{11}t + \frac{45}{121} - \frac{8}{10}C e^{11t} + c_2 e^t.$$

Note that the “ C ” in the formulas for $x(t)$ and $y(t)$ is the same number. The equations are coupled, so their constants are related.

5.2 #20. Write as

$$\begin{aligned}(D - 2)x - y &= -e^{2t} \\ -x + (D - 2)y &= 0\end{aligned}$$

Combine these to eliminate x : $(D - 2)(D - 2)x - x = 0$ or $x'' - 4x' + 3x = 0$. This has auxiliary equation $r^2 - 4r + 3 = (r - 3)(r - 1) = 0$ so $x(t) = c_1 e^{3t} + c_2 e^t$. The first equation then gives y : $y(t) = c_1 e^{3t} - c_2 e^t + e^{2t}$.

The initial conditions determine c_1, c_2 :

$$\begin{aligned}1 &= x(0) = c_1 + c_2 \\ -1 &= y(0) = c_1 - c_2 + 1,\end{aligned}$$

so $c_1 = -1/2$ and $c_2 = 3/2$. It follows that

$$\begin{aligned}x(t) &= -\frac{1}{2}e^{3t} + \frac{3}{2}e^t \\ y(t) &= -\frac{1}{2}e^{3t} - \frac{3}{2}e^t + e^{2t}.\end{aligned}$$

5.3 #5. See back of text.

5.3 #10. First we write the single second-order ODE as a system of first-order ODEs:

$$\begin{aligned}y' &= v \\ v' &= -tv - y.\end{aligned}$$

Here is a method for using MATLAB or OCTAVE as a calculator to quickly find the Euler’s method answer. Note that the up-arrow gets the last command so it is easy to repeatedly enter the same thing, even if that thing is mildly complicated:

```
>> h=0.25;
>> t=0, y=1, v=0
    t = 0
    y = 1
    v = 0
>> ynew=y+h*(v); vnew=v+h*(-t*v-y); t=t+h, y=ynew, v=vnew
    t = 0.25000
    y = 1
    v = -0.25000
>> ynew=y+h*(v); vnew=v+h*(-t*v-y); t=t+h, y=ynew, v=vnew
    t = 0.50000
    y = 0.93750
    v = -0.48438
>> [AGAIN]
>> ynew=y+h*(v); vnew=v+h*(-t*v-y); t=t+h, y=ynew, v=vnew
    t = 1
    y = 0.65186
    v = -0.73889
```

Thus, in particular, $y(1) \approx 0.65186$ by Euler’s method with $h = 0.25$.

(The exact answer is hard to come by. Using $h = 0.1$ gives $y(1) \approx 0.61852$ and using $h = 0.05$ gives $y(1) \approx 0.61160$. Probably the value of $y(1)$ is about 0.61)

5.3 #16. On this one I used the online applet at <http://www.csun.edu/~hcmth018/SysEu.html>. I entered “ $2*x-y$ ” in the first box, “ $3*x-6*y$ ” in the second box and then $x_0 = 0$, $y_0 = -2$, $b = 1$, $n = 8$. Note that $1/8 = 0.125 = h$. The result is:

t_n	x_n	y_n
0.00000	0.00000	-2.00000
0.12500	0.25000	-3.50000
0.25000	0.75000	-6.03125
0.37500	1.69141	-10.27344
0.50000	3.39844	-17.34424
0.62500	6.41608	-29.07800
0.75000	11.65485	-48.48048
0.87500	20.62862	-80.47027
1.00000	35.84455	-133.08723

How accurate is this anyway? In this case we can compare to the exact values of $x(t)$ and $y(t)$ because the actual solutions, a pair of functions of time, are given. The easiest way to compare is again to use MATLAB or OCTAVE to evaluate the formulas $x(t)$ and $y(t)$ at the same list of t values. Thus, from the exact solutions, the above numbers *should* be:

```
>> t=0:0.125:1; x=exp(5*t)-exp(3*t); y=exp(3*t)-3*exp(5*t);
>> [t' x' y']
ans =
```

```
0.00000    0.00000   -2.00000
0.12500    0.41325   -4.14975
0.25000    1.37334   -8.35403
0.37500    3.44060  -16.48224
0.50000    7.70080  -32.06579
0.62500   16.23908  -61.75887
0.75000   33.03335 -118.07551
0.87500   65.63527 -224.51494
1.00000  128.32762 -425.15394
```

The errors, the differences between the approximation and the exact values, grow rapidly in time.

Euler’s method does better with a smaller h value, however. (A method like Runge-Kutta can do much better even with the same h .) Here is Euler again but with h smaller by a factor of four. I have plotted the approximate and exact answers in Figure 1. Euler does better but the error is still obvious.

```
>> h = 1/32;
>> t = 0:h:1; xexact = exp(5*t)-exp(3*t); yexact = exp(3*t)-3*exp(5*t);
>> x(1) = 0; y(1) = -2;
>> for n=1:32, x(n+1) = x(n)+h*(2*x(n)-y(n)); y(n+1) = y(n)+h*(3*x(n)+6*y(n)); end
>> plot(t,xexact,t,yexact,t,x,'o',t,y,'o')
```

5.4 #5. See back of text.

5.4 #10. The critical points are the solutions of

$$0 = x^2 - 1$$

$$0 = xy.$$

Thus the critical points are $(-1, 0)$ and $(+1, 0)$. The xy -phase plane equation is

$$\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} = \frac{xy}{x^2 - 1}.$$

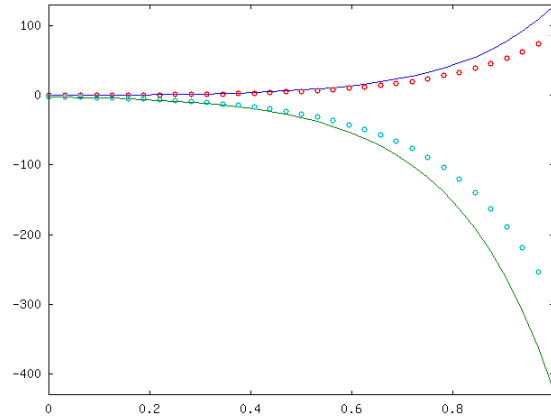


FIGURE 1. Exact (curve) and approximate (dots) solution to #16 in section 5.3.

This equation is separable:

$$\frac{dy}{y} = \frac{x}{x^2 - 1} dx$$

$$\ln |y| = \int \frac{x}{x^2 - 1} dx = \frac{1}{2} \ln |x^2 - 1| + C$$

$$y(x) = \begin{cases} A_0 \sqrt{1 - x^2}, & -1 \leq x \leq 1, \\ A_1 \sqrt{x^2 - 1}, & |x| \geq 1. \end{cases}$$

The number A_0 and A_1 do not have to be the same. These solutions meet the critical points.

There are two solutions (i.e. trajectories in the phase plane) that are semicircles. Namely if $-1 \leq x \leq 1$ and $A_0 = 1$ we have the upper semicircle of the unit circle. For the same x values and $A_0 = -1$ we have the lower semicircle of the unit circle. Figure 2 shows these solutions plus the direction field for the differential equation $\frac{dy}{dx} = \frac{xy}{x^2 - 1}$, in the xy -plane.

It is pretty easy to show that the other solutions are pieces of ellipses and of hyperbolas.

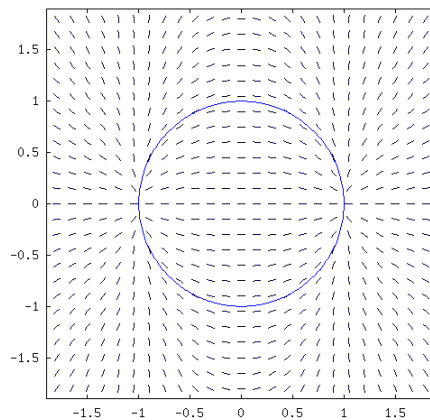


FIGURE 2. Semicircle solutions in xy -phase plane, to #10 in section 5.4.